

COMPENSATED OSCILLATOR CIRCUIT

5 Cross-Reference to Related Application:

This application is a continuation of copending International Application No. PCT/DE02/01996, filed May 29, 2002, which designated the United States and was not published in English.

10 Background of the Invention:

Field of the Invention:

Signal generators that can be used to produce sinusoidal oscillations are normally referred to as oscillators. In the case of LC oscillators, the frequency is governed by a resonant circuit with an inductance and a capacitance. The simplest method for producing a sinusoidal oscillation is to use an amplifier to compensate for attenuation of an LC resonant circuit.

20 The fundamental configuration of an oscillator such as this is described, for example, on pages 458 et seq. of a reference by Tieze, Schenk: entitled "Halbleiter-Schaltungstechnik [Semiconductor Circuit Technology]", 10th Edition 1993.

25 In order to achieve higher power levels and better efficiencies, oscillators are normally configured in the form

of push-pull oscillators, in which two cross-coupled transistors are provided for attenuation compensation, in which case the cross-coupling may, for example, be conductive, capacitive, inductive or transformer positive feedback.

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In order to make it possible to produce variable frequencies, it is also normal to configure the integrated capacitance in the LC resonant circuit to be controllable, for example, in the form of a varactor diode.

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When oscillator circuits are constructed in the form of integrated circuits, then, with normal manufacturing methods, this necessarily results in process fluctuations that, for example, result in capacitance value tolerances of $\pm 20\%$.

15 Discrepancies such as these from the nominal values of the components that are used cause amplitude discrepancies in the output signal from the oscillator, which are undesirable.

It is known for the bias current of the transistors that are
20 provided in the attenuation compensation amplifier, for example MOS field-effect transistors, to be readjusted such that the gradient of the transistors is adapted in a compensating manner. A dependent current source is normally provided for this purpose, although this increases the phase
25 noise of the oscillator. Furthermore, the compensating readjustment of the bias current of the transistors leads to a

shift in the operating point, and thus to a poorer drive capability for the transistor.

U.S. Patent No. 6,118,348 specifies a crystal oscillator
5 circuit. Two or more parallel-connected inverter stages are provided, and are connected to an oscillating crystal on the input side and output side. A control signal generator, which is coupled to the inverter stages, switches between different gain levels. The switching process is carried out with a
10 delay, so that the noise level in the output signal is low.

Summary of the Invention:

It is accordingly an object of the invention to provide a compensated oscillator circuit that overcomes the above-
15 mentioned disadvantages of the prior art devices of this general type, which compensates for manufacturing tolerances from the nominal values of the components used, and discrepancies resulting from these tolerances in the amplitude of the output signal, while the oscillator circuit at the same
20 time has good phase noise characteristics.

With the foregoing and other objects in view there is provided, in accordance with the invention, a compensated oscillator circuit. The compensated oscillator circuit
25 contains a supply potential connection, a resonant circuit, at least two attenuation compensation amplifiers coupled

switchably to the resonant circuit to compensate for attenuation, and switches. In each case one of the switches is coupled with in each case one of the attenuation compensation amplifiers for forming switchable current paths

5 between the resonant circuit and the supply potential connection. Currents sources are connected to and feed the attenuation compensation amplifiers. One of the current sources is disposed in each of the switchable current paths.

10 The attenuation compensation amplifiers which can be switched on and off separately from one another allow both the bias current of the amplifiers and the channel width to channel length ratio of the entire oscillator circuit, and hence the gradient of the gain, to be varied and thus to achieve an

15 oscillator output signal with a constant amplitude despite tolerance-dependent discrepancies in the component values from their nominal values. Since it is not only the bias current of the transistors that is changed, this reduces the dependency of both the supply current and the operating point

20 for the transistors on the actual component values. In this case, the attenuation compensation amplifiers are effectively connected into the oscillator circuit, or are disconnected from it, independently of one another, in order to achieve the desired oscillation amplitude at the output of the circuit,

25 for example, in order to compensate for manufacturing-dependent discrepancies from a desired oscillation amplitude.

The amplitude of the output signal from the oscillator circuit increases as the transistor gradient of the attenuation compensation amplified transistors increases. The gradient is
5 in this case approximately proportional to the square root of the product of the bias current and of the channel width to channel length ratio of the transistors.

Overall, the present invention makes it possible to
10 considerably reduce discrepancies from the ideal operating point of the oscillator amplifier, that is to say of the attenuation compensation amplifier. Thus, overall, this considerably reduces reductions in performance resulting in discrepancies of the components used from their nominal
15 values.

According to the present invention, the current paths each have a current source for feeding the attenuation compensation amplifiers.

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By way of example, switchable current sources may be used, which are each provided in one current path with in each case one attenuation compensation amplifier, in which case the attenuation compensation amplifiers may be permanently
25 connected to the common resonant circuit.

In one preferred embodiment of the present invention, the switches each have a control connection, which is connected to a drive circuit.

5 The drive circuit therefore makes it possible in a simple manner to select a specific combination of attenuation compensation amplifiers, in order in this way to set the desired overall gradient for the attenuation compensation for the oscillator and, in the end, thus to achieve the desired
10 oscillator signal amplitude.

In a further preferred embodiment of the present invention, a control loop is formed, with amplitude value detection, and is connected on the input side to the resonant circuit and on the
15 output side to the drive circuit.

The formation of a control loop allows automatic compensation for manufacturing-dependent component tolerances by measurement of the amplitude and by switching appropriate
20 attenuation compensation amplifiers on and off in a compensating manner.

In a further preferred embodiment of the present invention, the current paths with the attenuation compensation amplifiers
25 are connected in parallel with one another to the resonant circuit.

In a further preferred embodiment of the present invention, the attenuation compensation amplifiers each have two cross-coupled transistors.

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When using field-effect transistors, the cross coupling of the transistors can be achieved by connection of in each case one gate connection of a transistor in the transistor pair crossed over to in each case one drain connection of a further
10 transistor in the transistor pair.

The coupling may in this case be directly conductive, capacitive, or by transformer. The source connections of a transistor pair are connected directly to one another at a
15 source node, and are connected to a current source that can be switched on and off. This results in a switchable current path for feeding the attenuation compensation amplifiers.

In a further preferred embodiment of the present invention,
20 the transistors in the attenuation compensation amplifiers are MOSFET transistors, which have the same channel width to channel length ratio in pairs, with the channel width to channel length ratio of the attenuation compensation
amplifiers being graduated in binary steps with respect to one
25 another.

The binary graduation of the channel width to channel length ratios that influence the gradient allows a good compensation capability for manufacturing-dependent component tolerances, with a relatively small requirement for components and surface
5 area.

Depending on the field of use for the application of the oscillator circuit, other graduations of the transistor ratios in the attenuation compensation amplifiers with respect to one
10 another may, of course, also be worthwhile.

In a further preferred embodiment of the present invention, the switches are digitally driven transistor switches. Transistor switches based on CMOS or BiCMOS semiconductor
15 technology can be implemented in a simple manner and, furthermore, can be driven easily.

In a further preferred embodiment of the present invention, the resonant circuit has a control input for controlling the
20 oscillation frequency. The resonant circuit is normally in the form of an LC resonant circuit, and in this case the inductance is preferably fixed while the capacitance is controllable, for example, in the form of a varactor that can be driven by a control voltage.

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Other features which are considered as characteristic for the invention are set forth in the appended claims.

Although the invention is illustrated and described herein as embodied in a compensated oscillator circuit, it is nevertheless not intended to be limited to the details shown, since various modifications and structural changes may be made therein without departing from the spirit of the invention and within the scope and range of equivalents of the claims.

The construction and method of operation of the invention, however, together with additional objects and advantages thereof will be best understood from the following description of specific embodiments when read in connection with the accompanying drawings.

Brief Description of the Drawings:

Fig. 1 is a block diagram of a first exemplary embodiment of a compensated oscillator circuit according to the invention;

Fig. 2 is a simplified circuit diagram of a second embodiment of the compensated oscillator circuit; and

Fig. 3 is a circuit diagram of a third embodiment of the compensated oscillator circuit.

Description of the Preferred Embodiments:

Referring now to the figures of the drawing in detail and first, particularly, to Fig. 1 thereof, there is shown the principles of a compensated oscillator circuit in the form of a simplified block diagram with an LC resonator 1, to which a control voltage A can be supplied in order to set a desired oscillation frequency. The LC resonator 1 is connected to a reference ground potential via three parallel-connected current paths, each of which has an attenuation compensation amplifier 2, a current source 3 and a switch 4, in each case disposed connected in series. The attenuation compensation amplifiers 2 each have a negative impedance, in order to produce a system which can oscillate.

The switches 4 are connected by their control connections to a common drive circuit 5. The drive circuit 5 accordingly allows any one, two or three current paths to be effectively connected to or disconnected from the resonator 1, in each case independently of one another. The use of switches 4 to interrupt the current paths in each case interrupts the supply of the feed current to the attenuation compensation amplifiers 2.

Furthermore, an amplitude detector 6 is provided in order to provide automatic control, and its input is connected to an output of the oscillator circuit, and it is thus supplied with

an oscillator output signal B. The output of the amplitude detector 6 is connected to an input of the drive circuit 5.

Owing to the manufacturing tolerances (which are always
5 unavoidable when using mass production methods) with regard to the component values of the components used, for example capacitances, resistors, etc., discrepancies occur in the signal amplitude at the output oscillator signal B from a nominal amplitude. The discrepancies are evaluated in the
10 drive circuit 5, and the switches 4 in the individual current paths are driven as a function of the discrepancies in the amplitude that is provided from a nominal value, such that the desired nominal amplitude itself, or an amplitude with only a small discrepancy from the nominal amplitude, is set at the
15 output of the oscillator.

The gradient of the overall gain can be adjusted in a desired manner by connecting individual attenuation compensation amplifiers 2. This avoids any shift in the operating point
20 that would result from exclusive adaptation of the bias current of the attenuation compensation amplifiers, and which would lead to a deterioration in the drive capability and in the noise characteristics.

25 Fig. 2 shows a second exemplary embodiment of a compensated oscillator circuit that, apart from the feedback with the

amplitude detector 6 corresponds to the structure shown in the block diagram in Fig. 1, although it is in the form of a push-pull oscillator. For this purpose, the LC resonator 1 is configured to have two inductances 11, one connection of each is connected to a first supply potential connection 7, while a second connection of each is connected to one terminal of a capacitance 12.

The attenuation compensation amplifiers 2 each have two MOSFET transistors 21 which are cross-coupled in pairs, with their source connections being connected directly to one another, while a control connection is in each case connected to one connection of the capacitance 12. Furthermore, the transistors 21 are conductively cross-coupled, by in each case one gate terminal of one of the two transistors being connected to in each case one source terminal of the other transistor in the attenuation compensation amplifier 2. By way of example, a total of three attenuation compensation amplifiers 2 are provided, each of which is connected in the same way in parallel to the LC resonator 1. On the source side, one pair of transistors 21 in each signal path 2, 3, 4 are connected via a current source 3, which is in the form of a resistor, to a drain connection of an MOS field-effect transistor that is operated as a switch 4 and whose source connection is connected to a further supply potential

connection 8. The gate connection of the switching transistor 4 is connected to a drive circuit 5.

In order to adjust the amplitude of an output signal from the 5 described oscillator, the current paths 2, 3 and/or 4 can be selectively connected to or disconnected from the drive circuit 5, independently of one another, by appropriately switching the switches 4. In consequence, the gradient of the overall attenuation compensation in the oscillator is 10 adjustable. This is because the connection or disconnection of the feed currents for the attenuation compensation amplifiers 2 makes it possible to adjust the channel width to channel length ratio of the overall attenuation compensation. In the process, the desired optimum operating point of the 15 amplifiers is maintained.

This therefore allows compensation for manufacturing-dependent tolerances and avoidance of any amplitude discrepancy in the output signal from the oscillator using simple circuitry, 20 while the circuit at the same time has good phase noise characteristics.

Fig. 3 shows a development of the circuit shown in Fig. 2 as a voltage controlled oscillator. For this purpose, the 25 resonator 1 has a control input for supplying the control voltage A, which can be supplied to a variable capacitance 13

which, on a load side, is connected in the same way as the capacitor 12 shown in Fig. 2. The capacitance value of the capacitor 13 is accordingly dependent on the applied control voltage A. The variable capacitance 13 may, for example, be
5 formed by two varactor diodes.

Furthermore, the controllable oscillator in Fig. 3 has been developed by the oscillator output signal B being fed back to the drive circuit 5 by connecting the balanced output
10 connection of the resonator 1 to the drive circuit 5. This makes it possible to provide automatic compensation for tolerance-dependent changes in the amplitude of the output signal B, by the drive circuit 5 determining any discrepancy between the actual amplitude of the signal B and a nominal
15 amplitude and driving the switches 4 as a function of this discrepancy. The nominal amplitude may, for example, be stored in a memory in the drive circuit 5. As already described with reference to Figs. 1 and 2, the gradient of the attenuation compensation provided by the oscillator circuit
20 can be adjusted by the switch 4. For this purpose, the switches 4 can be switched on or off separately from one another. The other circuit blocks and components which are shown in Fig. 3, as well as their configuration and function, correspond to what has already been described with reference
25 to Fig. 2, and will therefore not be repeated once again at this point.

Instead of the illustrated conductive cross-coupling of the transistor pairs 21 in the attenuation compensation amplifier 2, it is of course possible to provide a different form of
5 coupling, for example capacitive or transformer coupling. Instead of the resistors, the current sources 3 may also be formed by more complex current sources.

The LC resonator 1 may also have a different structure to that
10 shown, as is normally known in the case of LC varactors.